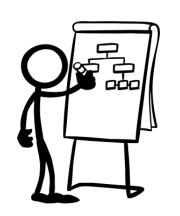
Planar Graph Euler's Formula DCEL



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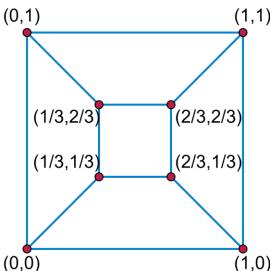
Based on slides by Yufei Zheng - 郑羽霏

Planar Graph

- Definition A planar graph is a graph that can be embedded in the plane
- Can be drawn on a plane in such a way that its edges intersect only at their endpoints
- In some pictures, a planar graph may have crossing edges

Planar Graph

- **Fáry's Theorem** every *simple planar* • • *graph* admits an embedding in the plane such that all edges are straight line segments which don't intersect.
- Simple graph undirected, no graph loops(self edges), no parallel edges
- Tutte Embedding the embedding of 3-vertex-connected planar graphs with good properties.



Euler's Formula

Notations

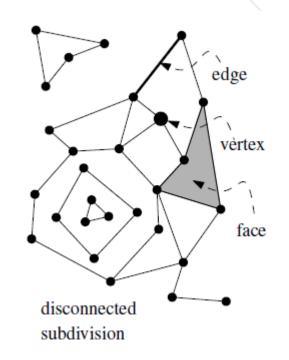
v – number of vertices

e – number of edges

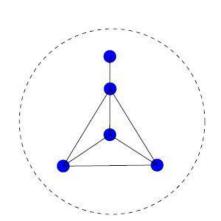
f – number of faces

Euler's Formula (for finite, connected planar graph)

$$v - e + f = 2$$



$$v = 5$$
 $e = 7$
 $f = 4$



v-e+f=2 - Proof by induction on F

© Base case: f = 1 acyclic connected graph – **Tree**

$$e = v - 1$$

 $v - e + f = v - (v - 1) + 1 = 2$

v-e+f=2 - Proof by induction on F

Olnduction step: Consider a graph with f' faces, v' vertices and e' edges.

Assume that the property holds for f = f' - 1

- a. Choose an edge that is shared by 2 different faces and remove it, the graph remains connected.
- b. This removal decreases both the number of faces and edges by one, on the new graph we get:

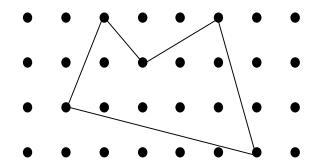
$$v-e+f = v'-(e'+1)+f'+1=2$$

 $\Rightarrow v'-e'+f'=2$

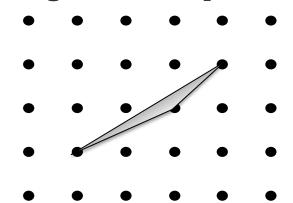
Applications of Euler's Formula

- Exercises:
- Show that for any planar graph:
- \circ Have at most 3V 6 edges.
- Have a vertex of degree at most 5.

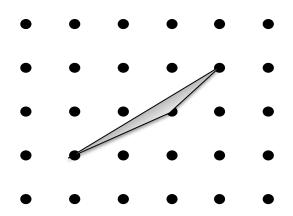
What is the area of this polygon?



OLet us begin with a simpler case, what is the area of a triangle containing no inner points:



O Lemma: the area of a triangle containing no inner points is $\frac{1}{2}$.



- O A basis of \mathbb{Z}^2 is a pair of vectors e_1, e_2 such that $\mathbb{Z}^2 = \{\lambda_1 e_1 + \lambda_2 e_2 \mid \lambda_1, \lambda_2 \in \mathbb{Z} \}$
- **Lemma:** If $\{(x_1, y_1), (x_2, y_2)\}$ is a basis of \mathbb{Z}^2 then $\det(A) = \pm 1$ where $A = \begin{pmatrix} x_1 & x_2 \\ y_1 & y_2 \end{pmatrix}$

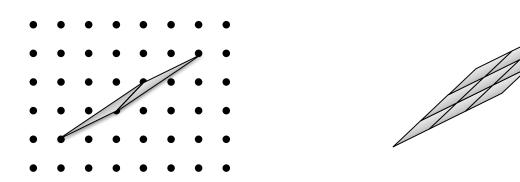
Proof:

There exists a matrix Q s.t. AQ = I

$$\Rightarrow \det(A)\det(Q) = 1$$

All the numbers are integers, hence the result.

 \bigcirc **Lemma:** If the triangle created by a pair of vectors contains no lattice points, this pair is a basis of \mathbb{Z}^2 .

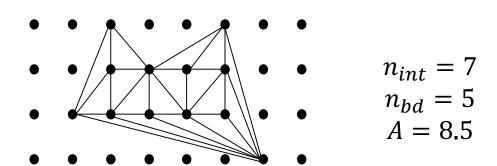


<u>Corrolary:</u> The area of a lattice triangle containing no inner points is $\frac{1}{2}$.

• <u>Pick's theorem:</u> The area of a polygon *Q*, with integral vertices is given by

$$A(Q) = n_{int} + \frac{1}{2}n_{bd} - 1$$

Where n_{int} is the number of interior points and n_{bd} are the numbers of boundary points in the interior.



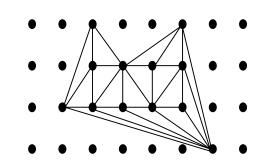
- Number of triangles: f 1
- Number of boundary edges: e_{bd}
- Number of interior edges: e_{int}

$$3(f-1) = 2e_{int} + e_{bd}$$

$$\Rightarrow f = 2(e-f) - e_{bd} + 3$$

$$= 2(n-2) - n_{bd} + 3$$

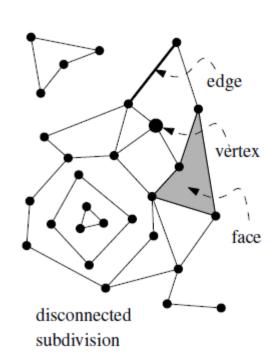
$$= 2n_{int} + n_{bd} - 1$$



$$A(Q) = \frac{1}{2}(f-1) = n_{int} + \frac{1}{2}n_{bd} - 1$$

DCEL - Doubly Connected Edge List

- OGiven a planar graph we are looking for a DS to represent the graph.
- We want to enable (for example):
- Traverse all edges incident to a vertex v
- Traverse all edges bounding a face
- Traverse all faces adjacent to a given face
- o etc...



DCEL - Doubly Connected Edge List

- **Complexity** of a subdivision = V + E + F
- DCEL A data structure for representing an embedding of a planar graph in the plane
- Only consider: every edge is a straight line segment
- Recall Fáry's Theorem
- DCEL consists of 3 collections of records:Vertices, Edges, Faces

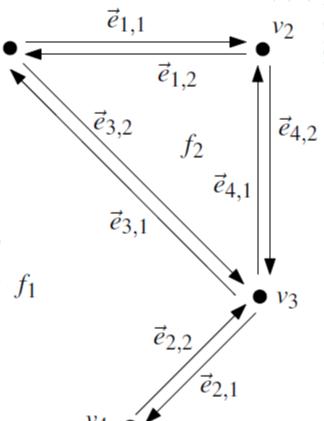
DCEL – A Record for Vertex

- Vertex the embedding of a node of the graph
- Coordinates(v) coordinates of vertices
- OIncidentEdge(v)
- Olimination of the contract of the contract

an edge and its endpoints a face and an edge on its boundary a face and a vertex of its boundary

Points to only one edge

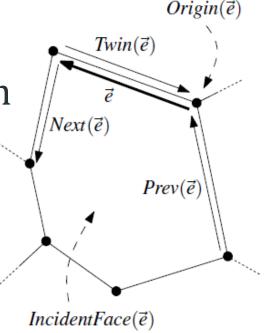
Vertex	Coordinates	IncidentEdge
v_1	(0,4)	$\vec{e}_{1,1}$
v_2	(2,4)	$\vec{e}_{4,2}$
v_3	(2,2)	$\vec{e}_{2,1}$
v_4	(1,1)	$\vec{e}_{2,2}$



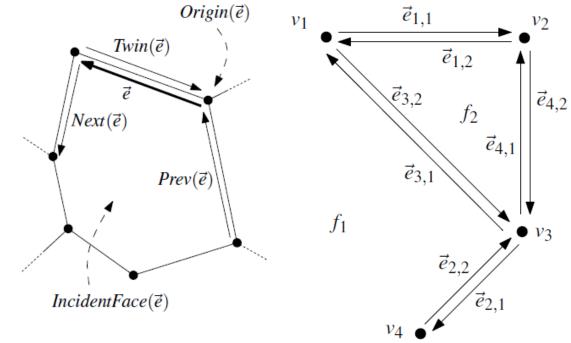
DCEL - A Record for Edge

- Half-edges different sides of an edge
- Bounds only 1 face
- Origin(e)
- Orientation the face it bounds lies to its left
- ID of a vertex structure
- Twin(e) the twin edge of e in the opposite direction
- OIncidentFace(e)
- Next(e) & Prev(e)

next and previous edge on the boundary of *IncidentFace*(*e*).



DCEL – A Record for Edge



Half-edge	Origin	Twin	IncidentFace	Next	Prev
$\vec{e}_{1,1}$	v_1	$\vec{e}_{1,2}$	f_1	$\vec{e}_{4,2}$	$\vec{e}_{3,1}$
$\vec{e}_{1,2}$	v_2	$\vec{e}_{1,1}$	f_2	$\vec{e}_{3,2}$	$\vec{e}_{4,1}$
$\vec{e}_{2,1}$	v_3	$\vec{e}_{2,2}$	f_1	$\vec{e}_{2,2}$	$\vec{e}_{4,2}$
$ec{e}_{2,2}$	v_4	$\vec{e}_{2,1}$	f_1	$\vec{e}_{3,1}$	$\vec{e}_{2,1}$
$\vec{e}_{3,1}$	v_3	$\vec{e}_{3,2}$	f_1	$\vec{e}_{1,1}$	$\vec{e}_{2,2}$
$ec{e}_{3,2}$	v_1	$\vec{e}_{3,1}$	f_2	$\vec{e}_{4,1}$	$\vec{e}_{1,2}$
$\vec{e}_{4,1}$	v_3	$\vec{e}_{4,2}$	f_2	$\vec{e}_{1,2}$	$\vec{e}_{3,2}$
$ec{e}_{4,2}$	v_2	$\vec{e}_{4,1}$	f_1	$\vec{e}_{2,1}$	$\vec{e}_{1,1}$

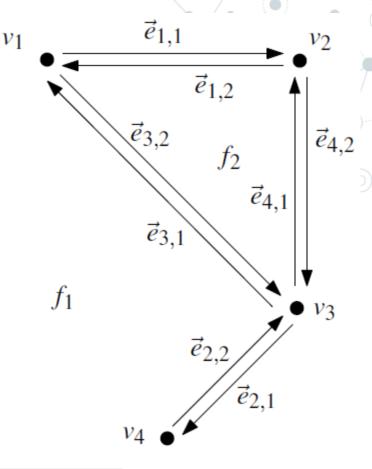
DCEL - A Record for Face

OuterComponent(f) -

A **pointer** to an half-edge on the outer boundary of face f.

OInnerComponents(f) -

A **list** contains for each hole in the face f a pointer to some half-edge on the boundary of the hole.



Face	OuterComponent	InnerComponents
$\overline{f_1}$	nil	$\vec{e}_{1,1}$
f_2	$ec{e}_{4,1}$	nil

DCEL – Further Facts

- Amout of Storage linear in the complexity of the subdivision
- vertices and edges linear in V+E
- faces

OuterComponent – linear in F InnerComponent lists– linear in E

Special cases

- For Isolated vertices in a face, store pointers
- For additional information, add attributes

DCEL - Exercises

- OTraverse all edges incident to a vertex v $e_2 = Next(Twin(e_1))$
- Why isn't the *Destination* field of the *Edge* structure needed?
 Origin(Twin(e))